

[Submit your solutions up to 07.12. before the Tutorial in LernraumPlus]

Symmetries in Physics - Homework Sheet No. 6

Exercise 6.1: (3 Points)

Consider the group of rotations, $SO(3)$, composed of the matrices;

$$R(\theta) = \left\{ \left(\begin{array}{ccc} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{array} \right) : \theta \in [0, 2\pi) \right\}. \quad (1)$$

By changing basis from $(\mathbf{e}_x, \mathbf{e}_y, \mathbf{e}_z)$ to $(\frac{1}{\sqrt{2}}(-\mathbf{e}_x + \mathbf{e}_y), \frac{1}{\sqrt{2}}(\mathbf{e}_x + \mathbf{e}_y), \mathbf{e}_z)$ show that this representation is completely reducible.

Compute the characters for each representation and comment on their value.

Exercise 6.2: (3 Points)

In a previous exercise you already encountered the Galilei group $\text{Gal}(3)$.

- (i) Show that a 5-dimensional linear representation of $\text{Gal}(3)$ consists of the matrices of the type

$$\begin{pmatrix} \mathbf{R} & \vec{v} & \vec{a} \\ \vec{0}^T & 1 & \tau \\ \vec{0}^T & 0 & 1 \end{pmatrix} \quad (2)$$

where $\vec{0}^T$ denotes a row vector with three zero entries, while \vec{v} and \vec{a} are two column vectors with three arbitrary real entries and \mathbf{R} is a three-dimensional rotation matrix, $\mathbf{R} \in SO(3)$.

- (ii) Is this representation faithful? Is it completely reducible?

Exercise 6.3: (4 Points)

Let us consider the $m \times m$ matrix

$$T = \begin{pmatrix} 0 & 1 & 0 & & \cdots & 0 \\ & 0 & 1 & 0 & & \\ \vdots & & \ddots & \ddots & \ddots & \vdots \\ 0 & & & & 0 & 1 \\ 1 & 0 & & \cdots & & 0 \end{pmatrix}, \quad (3)$$

i.e. $T_{ij} = 1$ for all $j - i = 1$ and for $i = m$ and $j = 1$ and otherwise $T_{ij} = 0$.

- (i) Construct a group, \tilde{G} , from T via matrix multiplication. The matrix group \tilde{G} is a representation of a finite group, G , you already know. Which group is this?
- (ii) With help of Maschke's theorem we know that the representation \tilde{G} is completely reducible. What are all irreducible representations of \tilde{G} ? Calculate for this purpose the eigenspaces of T .