

Exercise 6.1: Recall that for the KdV equation, the scaling dimensions of the variables are $[x] = 1$, $[u] = -2$, $[t] = 3$.

- (a) Deduce the scaling dimension of the Lax operators $L = \partial_x^2 + \frac{1}{6}u$ and B and explain why $[L, B]$ must be a multiplicative operator.
- (b) Give the most general operator that satisfies the scaling dimension and symmetries of B .
- (c) Show that,

$$[\partial_x^n, u] = \sum_{k=1}^n \binom{n}{k} \partial^k u \partial^{n-k}, \quad [\partial_x^2, u \partial_x] = \partial_x^2 u \partial_x + 2(\partial_x u) \partial_x^2, \quad [u \partial_x, u] = u(\partial_x u) \quad (1)$$

- (d) Using the results in (c), compute the commutator of the general operator from part (b) with L . By ensuring $[L, B]$ is a multiplicative operator, deduce an expression for B .
- (e) Recall that the n th KdV equation has the form $\partial_t u = \partial_x \left(\frac{\delta H_{n+1}}{\delta u(x)} \right)$. Deduce the general form of the B operator which will give the next equation (after the KdV) in the KdV hierarchy.

Exercise 6.2: Define the Pauli matrices,

$$\sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}. \quad (2)$$

Let $\sigma_{\pm} = \frac{1}{2}(\sigma_1 \pm i\sigma_2)$ and show,

$$\sigma_{\pm}^2 = 0, \quad \sigma_3^2 = I, \quad \sigma_{\pm} \sigma_3 = \mp \sigma_{\pm}, \quad \sigma_{\pm} \sigma_{\mp} = \frac{1}{2}(I \pm \sigma_3) \quad (3)$$

Exercise 6.3 : Recall the first order formalism for the Lax pairs. We replace the Schrodinger wave-function by $\Phi = (\phi_1, \phi_2)$, and we make the ansatz,

$$L = (\sigma_3 \partial_x - q(x, t) \sigma_+ + r(x, t) \sigma_-), \quad B = (P(x, t) \sigma_+ + Q(x, t) \sigma_- + R(x, t) \sigma_3) \quad (4)$$

so that the Lax equations become,

$$L\Phi = -i\zeta\Phi, \quad \partial_t \Phi = B\Phi. \quad (5)$$

By considering $\partial_x \partial_t \Phi = \partial_t \partial_x \Phi$, show that for the Lax equations to be consistent we require,

$$\partial_x R = qQ - rP \quad (6)$$

$$\partial_t r = Q_x - 2rR - 2i\zeta Q \quad (7)$$

$$\partial_t q = P_x + 2qR + 2i\zeta P. \quad (8)$$