

2.3 Schwinger-Dyson Equations and generating functionals

- using the path integral formalism we shall derive some relations that hold non-perturbatively. In preparation we need

• functional derivatives:

a functional $F[\phi]$ depends on a function ϕ just as the function $\phi(x)$ depends on a variable x

example: $S_E[\phi] = \int dx^4 \mathcal{I}_E(\phi(x), \partial_\mu \phi(x))$

Def functional derivative $\left[\frac{\delta F[\phi]}{\delta \phi(y)} = \lim_{\epsilon \rightarrow 0} \frac{F[\phi(\cdot) + \epsilon \delta(y-\cdot)] - F[\phi]}{\epsilon} \right]$

example: $F[\phi] = \int dx^4 \phi(x) \Rightarrow \frac{\delta F[\phi]}{\delta \phi(y)} = \lim_{\epsilon \rightarrow 0} \frac{\int dx^4 (\phi(x) + \epsilon \delta(y-x)) - \int dx^4 \phi(x)}{\epsilon} = 1$

ditto $F[\phi] = \int dx^4 \phi^n(x) \Rightarrow \frac{\delta F[\phi]}{\delta \phi(y)} = n \phi^{n-1}(y)$

$\Rightarrow \frac{\delta S_E[\phi]}{\delta \phi(y)} \stackrel{\text{Taylor}}{=} \int dx^4 \frac{\partial \mathcal{I}_E(\phi(x), \partial_\mu \phi(x))}{\partial \phi(x)} \delta(x-y) = \frac{\partial \mathcal{I}_E}{\partial \phi(y)}$

note: when differentiating we do not treat $\phi, \partial_\mu \phi$ as indep variables but differentiate both w.r.t ϕ :

e.g. for $\mathcal{I}_E = \frac{1}{2} \partial_\mu \phi(x) \partial_\mu \phi(x) + \frac{m^2}{2} \phi(x)^2 + \frac{g}{3!} \phi(x)^3 + \frac{\lambda}{4!} \phi(x)^4$

we get $\frac{\delta S_E[\phi]}{\delta \phi(y)} = -\frac{1}{2} \partial_\mu \partial_\mu \phi(y) + m^2 \phi(y) + \frac{g}{2!} \phi^2(y) + \frac{\lambda}{3!} \phi^3(y)$

Schwinger - Dyson equations:

These follow from 'trivial' identities, such as integrals of total derivatives

• discrete: $0 = \int_{-\infty}^{\infty} d\vec{v} \frac{d}{d\vec{v}_\mu} \left\{ e^{-S_E(\vec{v})} \right\} = \int_{-\infty}^{\infty} d\vec{v} \frac{d}{d\vec{v}_\mu} \left\{ v_\mu v_\nu \dots e^{-S_E(\vec{v})} \right\}$ for b.c. $S(\vec{v}) \rightarrow \infty$ as $|\vec{v}| \rightarrow \infty$

• continuous: $0 = \int \mathcal{D}\phi \frac{\delta}{\delta\phi(x)} \left\{ e^{-S_E[\phi]} \right\} = \int \mathcal{D}\phi \frac{\delta}{\delta\phi(x)} \left\{ \phi(y) \phi(z) \dots e^{-S_E[\phi]} \right\}$ for appropriate b.c.

back to our example:

Γ : $0 = \int \mathcal{D}\phi \left\{ [-\partial_\mu^2 + m^2] \phi(x) + \frac{1}{3!} \phi^3(x) \right\} e^{-S_E[\phi]}$

\Rightarrow $0 = [-\partial_\mu^2 + m^2] \langle \phi(x) \rangle + \frac{1}{3!} \langle \phi^3(x) \rangle + \frac{g}{2} \langle \phi^2(x) \rangle$

classical equations of motion hold for expectation values!

• get all identities: use generating functional $Z[J]$

Def $Z[J] = \int \mathcal{D}\phi e^{-S_E[\phi] + \int dx^4 J(x) \phi(x)}$ including source $J(x)$

this can be used to express all the above identities:

• we have $\frac{\delta^n Z[J]}{\delta J(x_1) \dots \delta J(x_n)} = \int \mathcal{D}\phi \phi(x_1) \dots \phi(x_n) e^{-S_E[\phi] + \int dx^4 J(x) \phi(x)}$

i.e. $G_E^{(n)}(x_1, \dots, x_n) = \langle \phi(x_1) \dots \phi(x_n) \rangle = \frac{\delta^n Z[J]}{\delta J(x_1) \dots \delta J(x_n)} \Big|_{J=0} / Z[0]$

• Normalise $Z[0] \equiv 1$

$\Rightarrow Z[J] = \sum_{n=0}^{\infty} \frac{1}{n!} \int dx_1 \dots dx_n \frac{\delta^n Z[J]}{\delta J(x_1) \dots \delta J(x_n)} \Big|_{J=0} J(x_1) \dots J(x_n)$ Taylor expansion

$= \sum_{n=0}^{\infty} \frac{1}{n!} \int dx_1 \dots dx_n G_E^{(n)}(x_1, \dots, x_n) J(x_1) \dots J(x_n)$

is the generating functional for all Green functions

Schwinger-Dyson eq for Z[J]

(4)

$$0 = \int \mathcal{D}\phi \frac{\delta}{\delta\phi(x)} \left\{ e^{-S_E[\phi] + \int d^4y J(y)\phi(y)} \right\}$$

$$= \int \mathcal{D}\phi \left\{ -\frac{\partial I_E}{\partial\phi(x)} + J(x) \right\} e^{-S_E[\phi] + \int d^4y J(y)\phi(y)} \quad (*)$$

• we can generate any polynomial $(\phi(x))^n$ by $\frac{\delta^n}{(\delta J)^n}$:

$$\int \mathcal{D}\phi (\phi(x))^n e^{-S_E + \int J\phi} = \int \mathcal{D}\phi \left[\frac{\delta}{\delta J(x)} \right]^n e^{-S_E + \int J\phi}$$

and if we consider $\frac{\partial I_E}{\partial\phi(x)} \equiv I'_E(\phi(x))$ as a polynomial in $\phi(x)$ (\rightarrow exp)

$$\text{we have } (*) : 0 = \int \mathcal{D}\phi \left\{ -I'_E\left(\frac{\delta}{\delta J(x)}\right) + J(x) \right\} e^{-S_E + \int J\phi} \Leftrightarrow \boxed{0 = \left[-I'_E\left(\frac{\delta}{\delta J(x)}\right) + J(x) \right] Z[J]}$$

$\underbrace{\hspace{10em}}_{\phi(x)\text{-indep.}} \qquad \qquad \qquad \text{S.O. eq.}$

• our example:

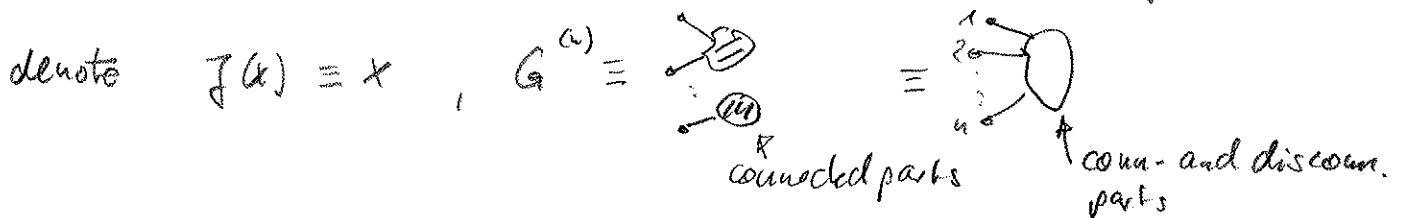
$$I_E(\phi(x)) = \frac{1}{2} \phi \Delta^{-1} \phi(x) + \frac{g}{3!} \phi^3(x) + \frac{1}{4!} \phi^4(x), \quad \Delta^{-1} = -\partial_\mu^2 + m^2$$

$$\Rightarrow I'_E(\phi) = \Delta^{-1} \phi(x) + \frac{g}{2!} \phi^2(x) + \frac{1}{3!} \phi^3(x)$$

$$\Rightarrow \text{S.O. eq.} : -\left[\Delta^{-1} \frac{\delta}{\delta J(x)} + \frac{g}{2!} \left(\frac{\delta}{\delta J(x)}\right)^2 + \frac{1}{3!} \left(\frac{\delta}{\delta J(x)}\right)^3 - J(x) \right] Z[J] = 0$$

Graphical representation

use that $Z[J]$ generates all $G_n^{(n)}$ (decorated with $J(x_1) \dots J(x_n)$)



$$\Rightarrow Z[J] = 1 + \int J(x) G_1^{(1)} + \frac{1}{2!} \int J(x) J(y) G_2^{(2)}(x,y) + \frac{1}{3!} \int J(x) J(y) J(z) G_3^{(3)}(x,y,z) + \dots \equiv \square$$

$\Delta(x, y) = \langle \phi(x) | \phi(y) \rangle$ is the Euclidean Green's function

$\Rightarrow \Delta^{-1} \Delta = 1$

denote $\Delta(x, y) = \text{---} \overset{x}{\bullet} \text{---} \overset{y}{\bullet} \text{---}$, $g \equiv \text{---} \overset{x}{\bullet} \text{---}$, $1 \equiv \overset{x}{\times}$

$\frac{\delta Z[J]}{\delta J(y)} = \text{---} \overset{x}{\bullet} \text{---} \bigcirc + \text{---} \overset{x}{\bullet} \text{---} \bigcirc \overset{x}{\times} + \frac{1}{2!} \text{---} \overset{x}{\bullet} \text{---} \bigcirc \overset{x}{\times} \overset{x}{\times} + \frac{1}{3!} \text{---} \overset{x}{\bullet} \text{---} \bigcirc \overset{x}{\times} \overset{x}{\times} \overset{x}{\times} + \dots = \text{---} \text{---} \square$

↑
argument y

S-D eq: $\Delta^{-1} \frac{\delta}{\delta J(x)} Z[J] = \left[-\frac{g}{2} \left(\frac{\delta}{\delta J} \right)^2 - \frac{1}{6} \left(\frac{\delta}{\delta J} \right)^3 + J \right] Z[J]$

$\Delta \Rightarrow \frac{\delta}{\delta J(x)} Z[J] = \Delta \left[J - \frac{g}{2} \left(\frac{\delta}{\delta J} \right)^2 - \frac{1}{6} \left(\frac{\delta}{\delta J} \right)^3 \right] Z[J]$

$\text{---} \text{---} \square = \text{---} \overset{x}{\times} \square - \frac{1}{2} \text{---} \overset{x}{\bullet} \text{---} \square - \frac{1}{6} \text{---} \overset{x}{\bullet} \text{---} \square$

as $\frac{\delta^2}{(\delta J(x))^2} Z[J] = \bigcirc \overset{x}{\times} \bigcirc + \frac{1}{2} \bigcirc \overset{x}{\times} \bigcirc \overset{x}{\times} + \dots$

$\Rightarrow \Delta \frac{\delta^2}{(\delta J)^2} Z = \text{---} \overset{x}{\bullet} \text{---} \bigcirc \overset{x}{\times} \bigcirc + \text{---} \overset{x}{\bullet} \text{---} \bigcirc \overset{x}{\times} \bigcirc \overset{x}{\times} + \frac{1}{2} \text{---} \overset{x}{\bullet} \text{---} \bigcirc \overset{x}{\times} \bigcirc \overset{x}{\times} \bigcirc \overset{x}{\times} + \dots = \text{---} \text{---} \square$

etc

$\left(\frac{\delta}{\delta J(y)} \right)$ deletes a $\overset{x}{\times}$ and joins it with the other endpoint

with argument y $\frac{\delta}{\delta J} \text{---} \overset{x}{\bullet} \text{---} \bigcirc \overset{x}{\times} \bigcirc = \text{---} \bigcirc \overset{x}{\times} \bigcirc$

we can now iterate by reinserting the S.O. eq into itself:

evaluate $\Delta \cdot \frac{g}{2} \left(\frac{S}{Sf(x)} \right)^2$ - term by reinserting the S.O.

$$\frac{S}{Sf(y)} \frac{S}{Sf(x)} Z[\gamma] = \frac{S}{Sf(y)} \left\{ \begin{aligned} & \bullet \text{---} x \square - \frac{1}{2} \bullet \text{---} \bigcirc \square - \frac{1}{6} \bullet \text{---} \bigcirc \square \end{aligned} \right\}$$

$$= \begin{aligned} & \bullet \text{---} x \square + \bullet \text{---} x \bullet \text{---} y \square - \frac{1}{2} x \bullet \text{---} \bigcirc \square - \frac{1}{6} \bullet \text{---} \bigcirc \square \end{aligned}$$

- take the limit $x \rightarrow y$ (merge)
- and multiply with Δ

$$\Rightarrow \frac{S}{Sf(x)} Z[\gamma] = \Delta \left[\gamma - \frac{g}{2} \left(\frac{S}{Sf(x)} \right)^2 - \frac{1}{6} \left(\frac{S}{Sf(x)} \right)^3 \right] Z[\gamma]$$

$$\Leftrightarrow \bullet \text{---} \square = \bullet \text{---} x \square - \frac{1}{2} \left\{ \begin{aligned} & \bullet \text{---} \bigcirc \square + \bullet \text{---} \bigcirc \square - \frac{1}{2} \bullet \text{---} \bigcirc \square \\ & - \frac{1}{6} \bullet \text{---} \bigcirc \square \end{aligned} \right\}$$

$O(g^2)$

$$- \frac{1}{6} \left\{ \dots \right\}$$

- if we want to return to a perturbative expansion

here we may use another iteration for $\frac{S^3}{Sf^3}$

we can drop higher order terms after iteration:

to order $O(g^2), O(1)$

$$\bullet \text{---} \square = \bullet \text{---} x \square - \frac{1}{2} \bullet \text{---} \bigcirc \square - \frac{1}{2} \bullet \text{---} \bigcirc \square + \dots$$

$$= \bullet \text{---} x \square - \frac{1}{2} \bullet \text{---} \bigcirc \square - \frac{1}{2} \bullet \text{---} \bigcirc \square + \dots = \bullet \text{---} x \square + O(g)$$

$$\Leftrightarrow \frac{\bullet \text{---} \square}{\square} = \bullet \text{---} x - \frac{1}{2} \bullet \text{---} \bigcirc - \frac{1}{2} \bullet \text{---} \bigcirc + \dots$$

Other generating functionals

A) $W[J] = \ln(Z[J]) \Leftrightarrow Z[J] = e^{W[J]}$

• generates all connected Green's functions $G_{EC}^{(n)}$

$$W[J] = \sum_{n=0}^{\infty} \frac{1}{n!} \int dx_1 \dots dx_n G_{EC}^{(n)}(x_1 \dots x_n) J(x_1) \dots J(x_n)$$

(proof to order 4 : ex 6.1)

• S.D. eq for $W[J]$: $\int \left(\frac{\delta W[J]}{\delta J(x)} + \frac{\delta}{\delta J(x)} \right) \mathbb{1} = J(x)$
 (with $\frac{\delta}{\delta J(x)} \mathbb{1} = 0$)

B) Legendre transform $\Phi(x) \equiv \frac{\delta W[J]}{\delta J(x)} \Rightarrow$

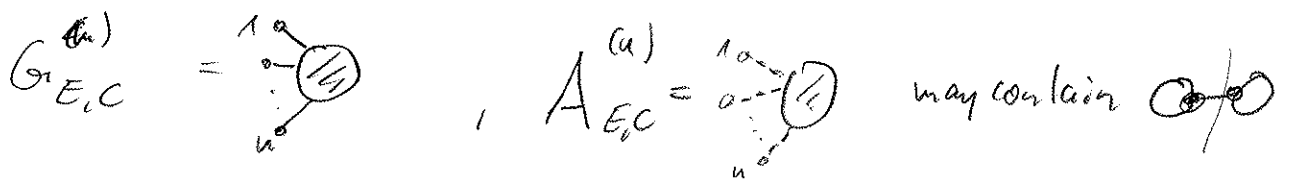
$$\Gamma[\Phi] \equiv W[J] - \int dx \Phi(x) J(x)$$


$\Rightarrow \frac{\delta \Gamma[\Phi]}{\delta \Phi(x)} = -J(x)$; if we set $J=0$ at the end $\frac{\delta \Gamma}{\delta \Phi} = 0$ is the eq. for an extremum

• S.D. eqs for $\Gamma \rightarrow$ ex 6.2

• Taylor $\Gamma[\Phi] = \sum_{n=0}^{\infty} \frac{1}{n!} \int dx_1 \dots dx_n \Gamma_E^{(n)}(x_1 \dots x_n) \Phi(x_1) \dots \Phi(x_n)$

generates the 1-particle-irreducible (1PI) Green's funct:



1PI =  does not contain diagrams that become disconnected when cutting 1 line