

Invariants:

- $\psi^a \varphi_a = \epsilon^{ab} \psi_b \varphi_a$ is invariant under $SU(2)$ transformations for general spinors ψ_a, φ_a and thus is a scalar quantity:

$$\begin{aligned} \underline{\psi^a \varphi_a} &= \epsilon^{ab} \psi_b^1 \varphi_a^1 \\ &= \epsilon^{ab} U_b^d \psi_d U_a^c \varphi_c = (U^T C U)^{cd} \psi_d \varphi_c \\ &= C^{cd} \psi_d \varphi_c = \epsilon^{cd} \psi_d \varphi_c = \underline{\psi^c \varphi_c} \end{aligned}$$

- a generic tensor $T^{a_1 a_2 \dots b_1 b_2 \dots}$ transforms w.r.t. U^* for the upper and w.r.t. U for the lower indices. Any index pair contracted with ϵ^{ab} does not transform:

$$T^{a_1 a_2 \dots a_n}_{b_1 b_2 \dots b_m} = U^{*a_1}_{c_1} \dots U^{*a_n}_{c_n} U_{b_1}^{d_1} \dots U_{b_m}^{d_m} T^{c_1 \dots c_n}_{d_1 \dots d_m}$$

- by contracting spinors and tensors appropriately we can build other invariants

Higher-dimensional tensor irreps & Clebsch-Gordan coefficients

- the product of the two spinors ψ_a and φ_b (each forming an $SU(2)$ irrep) can be combined into 4 different ways:

$$\begin{aligned} \psi_a \varphi_b, a, b = 1, 2: & \quad \left. \begin{array}{l} \psi_1 \varphi_1 \\ \psi_2 \varphi_2 \\ \psi_1 \varphi_2 + \psi_2 \varphi_1 \end{array} \right\} \begin{array}{l} \text{symmetric in} \\ \text{indices} \end{array} \quad \begin{array}{l} \text{spin } 1 \\ \text{multiplet} \end{array} \\ & \quad \left. \begin{array}{l} \psi_1 \varphi_2 - \psi_2 \varphi_1 = \epsilon^{cd} \psi_d \varphi_c \end{array} \right\} \begin{array}{l} \text{antisym. in indices,} \\ \text{is invariant under } SU(2) \\ \Leftrightarrow \text{has spin } 0 \end{array} \end{aligned}$$

as a Clebsch-Gordan series (see p. 19)

this is $\frac{1}{2} \otimes \frac{1}{2} = 1 \oplus 0 = \sum_{c=|l_1-l_2|}^{l_1+l_2} \oplus a_c 0^{(c)}$ (sometimes the dim $2j+1$ of the rep is used instead: $2 \otimes 2 = 3 \oplus 1$)

- so far we have constructed $SU(2)$ tensor reps of rank 1 (vectors) and rank 2 (matrix). This can be continued as follows:

rank 3: - combine sym. tensor $\psi_{ca} \psi_b$ with χ_c
 (- the combination of $\psi_{ca} \psi_b$ with χ_c leads again to rank 1 as $\sim \psi_a \psi_a$ which is an invariant. This is a peculiarity of $SU(2)$)

Clebsch - Gordon: $1 \otimes \frac{1}{2} = \frac{3}{2} \oplus \frac{1}{2}$ (or $3 \otimes 2 = 4 \oplus 2$)

Yang diagram: $\square \otimes \square = \square \oplus \square$

explicitly:

$$\psi_{ca} \psi_b \chi_c = \frac{1}{3} \left\{ \begin{aligned} & (\psi_{ca} \psi_b) \chi_c + \psi_{cb} \psi_c \chi_a + \psi_{cc} \psi_{ca} \chi_b && \text{totally sym.} \\ & + (\psi_{ca} \psi_b) \chi_c - \psi_{cb} \psi_c \chi_a && \text{antisym in ac} \\ & + (\psi_{ca} \psi_b) \chi_c - \psi_{cc} \psi_{ca} \chi_b && \text{antisym in bc} \end{aligned} \right\}$$

$\sim \epsilon_{ac} \psi_{cb} \chi_d$
 $\sim \epsilon_{bc} \psi_{ca} \chi_d$
 $\cong \chi_a$

• $SU(3)$ Tensors:

the fundamental irrep of $SU(3)$ acts on 3 component spinors $\psi_{a=1,2,3}$

$$\psi'_a = U_a^b \psi_b, \quad U \in SU(3), \quad \text{often denoted by } \mathbf{3} \quad \square$$

In contrast to $SU(2)$ complex conjugation is no longer an automorphism

$$\psi^a = U^{*a}_b \psi^b \quad U \in SU(3), \quad \text{denoted by } \overline{\mathbf{3}} \Leftrightarrow \mathbf{3}$$

* the ϵ -tensor is again an invariant (ϵ_{abc} tot. antisym with $\epsilon_{23} = +1$);
 = 1 due to $SU(3)$

$$\epsilon^a_{bc} = U_a^d U_b^e U_c^f \epsilon_{def} \stackrel{\text{check}}{=} \det(U) \epsilon_{abc} = \epsilon_{abc}$$

like wise is the ϵ -tensor with upper indices invariant, due to $\det(U^*) = (\det U)^* = 1^* \Rightarrow \epsilon^{abc} = U^{*a} U^{*b} U^{*c} \epsilon^{\det} = \det U^* \epsilon^{abc}$

* the ϵ -tensor can again be used to build invariants and to raise indices:

Examples: • $\psi^a = \epsilon^{abc} \varphi_b \xi_c = \epsilon^{abc} \frac{1}{2} \varphi_{[b} \xi_{c]}$ □

transforms like a spinor with upper index as

$$\psi'^a = \epsilon^{'abc} \varphi'_b \xi'_c = U^{*a} U^{*b} U^{*c} \underbrace{U_b^g U_c^h}_{U^{*g} U^{*h}} \epsilon^{\det} \varphi_g \xi_h$$

$$= U^{*a} U^{*g} U^{*h} \epsilon^{dgh} \varphi_g \xi_h = U^{*a} \psi^d$$

$U^{*g} U_b^g = \delta^{*g}_b$

• complete contractions like $\chi_a \psi^a$ transform like scalars and are thus invariants:

$$\chi'_a \psi'^a = U_a^b U^{*a} \chi_b \psi^c = \underbrace{U_c^a U_a^b}_{\delta_c^b} \chi_b \psi^c = \chi_b \psi^b$$

* note that in both cases we only used the unitarity of $U \in SU(3)$, it is not necessary for $*$ to be an automorphism to show this.

Higher dimensional irreps of $SU(3)$:

as for $SU(2)$ we will give a few examples and draw the corresponding Young tableaux. The simplest example is as in $SU(2)$ to combine $q\bar{q}$ (meson)

• $\chi_a \bar{\psi}^b = \underbrace{(\psi_a \bar{\psi}^b - \frac{1}{3} \delta_a^b \psi_c \bar{\psi}^c)}_{\text{an invariant part}} + \frac{1}{3} \delta_a^b \psi_c \bar{\psi}^c$ where we split off an invariant part \swarrow s.t.h. the remainder is traceless.

* We have 9 possible combinations of indices $a, b = 1, 2, 3$

and it turns out that the traceless part transforms irreducibly:

$$3 \otimes \bar{3} = 8 \oplus 1 \quad (\text{here in 2jz notation), or}$$

$$\square \otimes \square = \square\square \oplus \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array}$$

The Young-tableaux reflect the index structure of the lower indices,

so here $\bar{3}$ given by $\bar{\Psi}^a = \epsilon^{abc} T_{bc3}$ where T is an anti-

Symmetric tensor, rep. by \square . The combination $\begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array}$ is then totally antisym. in all lower indices (example $q=(u,d,s) \Rightarrow \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} = \epsilon_{q_1 q_2 q_3} \begin{pmatrix} u \\ d \\ s \end{pmatrix}$) and an octet ($\pi^\pm, \pi^0, K^\pm, K^0, \bar{K}^0, \eta, \eta'$).

- in order to build Baryons qqq we first need to consider the building blocks qq :

$$\Psi_a \Psi_b = \frac{1}{2} (\Psi_{[a} \Psi_{b]} + \Psi_{\{a} \Psi_{b\}})$$

where the antisym. part looks like a vector with upper indices (an antisym. 3×3 matrix has 3 indep components): thus this corresponds

$$\text{to } 3 \otimes 3 = 6 \oplus \bar{3}$$

$$\text{or } \square \otimes \square = \square\square \oplus \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array}$$

- combining $\Psi_a \Psi_b$ with Ψ_c we can symmetrize or antisym. c with (a,b) to get $6 \otimes 3 = 10 \oplus 8$, $S_{(abc)}$ has 10 comp (3 all equal, 6 where 2 equal, +1 where all different)
- or $\square \otimes \square = \square\square \oplus \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array}$ (looks as for $S_{(abc)}$, but with different dim.)

- we also may combine $\Psi_{[a} \Psi_{b]}$ with Ψ_c which is $\bar{3} \otimes 3$ as above

$$\Rightarrow \text{in total } 3 \otimes 3 \otimes 3 = 10 \oplus 8 \oplus 8 \oplus 1$$

III Coordinate Transformations: the Lorentz and Poincaré Group

Notation: Lorentz group = rotations, boost, P&T, Poincaré = Lorentz + translations in detail.

* Postulate of Homogeneity of Space-Time:

- the physics does not change:
 - in time & at different points in space
 - when moving from 1 frame of inertia to another

→ Symmetries:

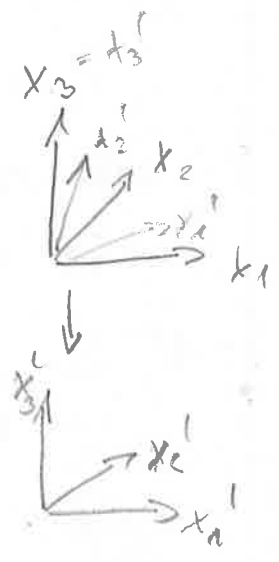
∴ translation in time & translation in space $\left\{ \begin{array}{l} t' = t + a_0 \\ \vec{x}' = \vec{x} + \vec{a} \end{array} \right.$ or $x_\mu' = x_\mu + a_\mu, \mu=0,1,2,3$
 $x_0 = ct, (x_1, x_2, x_3) = \vec{x}$

(Noether: conservation of energy and momentum)

* rotations (see p. 32, p 4)

e.g. around x_3 axis
 by $\varphi \in [0, 2\pi)$
 compact

$$\begin{aligned} x_0' &= x_0 \\ x_1' &= x_1 \cos \varphi - x_2 \sin \varphi \\ x_2' &= x_1 \sin \varphi + x_2 \cos \varphi \\ x_3' &= x_3 \end{aligned}$$



* classical mechanics - Galilei trafo

$$\begin{cases} x_0' = x_0 \\ x_j' = x_j - \frac{v_j}{c} x_0 \end{cases}$$

* relativistic mechanics - Lorentz trafo

e.g. boost in x_3 direction

$$\begin{cases} x_0' = \gamma (x_0 - x_3 \frac{v}{c}) \\ x_1' = x_1 \\ x_2' = x_2 \\ x_3' = \gamma (x_3 - x_0 \frac{v}{c}) \end{cases}$$

where $\gamma(v) = (1 - \frac{v^2}{c^2})^{-\frac{1}{2}}$
 $\equiv \cosh \zeta, \zeta \in [0, \infty)$
 $\frac{v}{c} = \tanh \zeta$ non-compact

non-relativistic limit $c \rightarrow \infty$

$$\begin{cases} x_0' = x_0 \cosh \zeta - x_3 \sinh \zeta \\ x_1' = x_1 \\ x_2' = x_2 \\ x_3' = x_3 \cosh \zeta - x_0 \sinh \zeta \end{cases}$$

We also may have as symmetries

* Time reversal T : $x_0' = -x_0$
 $x_j' = +x_j$

(H-atom + \vec{B} -field is not
 T invariant)

* parity P : $x_0' = +x_0$
 $x_j' = -x_j$

→ classical invariant:

the Euclidean distance between 2 points \vec{x} and \vec{y} is invariant.

$$\underbrace{(\vec{x}' - \vec{y}')^2}_{= (\vec{x} - \vec{y})^2} = (x_j - y_j)(x_j - y_j) \equiv \underbrace{\|\vec{x} - \vec{y}\|^2}_{\text{(incl. } \|\vec{x}\| \text{ for distance } \vec{0})}$$

under • Galilei (trivial), • rotations as these are orthogonal transformations $\Theta \Theta^T = \mathbb{1}$ that preserve the scalar product (and have $\det \Theta = +1$)

• Parity P, and combination of P & rotations, thus gives the second half of orthogonal transformations with $\det \Theta = -1$ (disconnected from $\mathbb{1}$)

→ relativistic invariant:

propertime

$$\underbrace{(x_0' - y_0')^2 - (x_j' - y_j')(x_j' - y_j')}_{= c^2 \tau_{rel}^2} = (x_0 - y_0)^2 - (\vec{x} - \vec{y})^2$$

obvious by this remains invariant under rotations, P, combinations of the, it is also invariant under T, and combination of rotation and P

• it is also invariant under Lorentz boost

$$\begin{aligned} \text{e.g. } (x_0' - y_0')^2 - (x_j' - y_j')^2 &= ((x_0 - y_0) \cosh \eta - (x_3 - y_3) \sinh \eta)^2 - (x_1 - y_1)^2 - (x_2 - y_2)^2 \\ &\quad - ((x_3 - y_3) \cosh \eta - (x_0 - y_0) \sinh \eta)^2 \\ &= ((x_0 - y_0)^2 - (x_3 - y_3)^2) (\cosh^2 \eta - \sinh^2 \eta) - (x_1 - y_1)^2 - (x_2 - y_2)^2 \end{aligned}$$

as well as combinations of boosts, P, T and rotations

• defining $\vec{u} = \frac{d\vec{x}}{dt}$ the 4-momentum vector $p_\mu = p(u)(mc, m\vec{u}) \equiv (\frac{E}{c}, \vec{p})$ of a particle with mass m leadsto invariant under Lorentz trafo

$$m^2 c^2 = p_\mu p^\mu = \left(\frac{E}{c}\right)^2 - \vec{p}^2$$

the Lorentz group, $SO(3,1)$ and $S\mathbb{L}(2, \mathbb{C})$:

the properties can be best analysed introducing

the metric $\eta = \text{diag}(1, -1, -1, -1)$ Minkowski \sim

upper indices $X^\mu = \eta^{\mu\nu} X_\nu$ $(= (x_0, -x_1, -x_2, -x_3))$

scalar product $X^\mu Y_\mu = \eta^{\mu\nu} X_\nu Y_\mu$, norm $X^\mu X_\mu = x_0^2 - x_1^2 - x_2^2 - x_3^2 = \|X\|_4^2$

Lorentz trafo $X'_\mu = \Lambda_\mu^\nu X_\nu$, $\Lambda_\mu^\nu \in \text{GL}(4, \mathbb{R})$

\rightarrow the Lorentz group are all trafos that leave the above scalar product with Minkowski metric invariant

$$X'^\mu X'_\mu = \eta^{\mu\nu} X'_\nu X'_\mu = \eta^{\mu\nu} \Lambda_\mu^\alpha \Lambda_\nu^\beta X_\alpha X_\beta \stackrel{!}{=} \eta^{\alpha\beta} X_\alpha X_\beta$$

$$\Leftrightarrow \boxed{(\Lambda^T \eta \Lambda)^{\alpha\beta} = \eta^{\alpha\beta}} \quad (*) \quad \Leftrightarrow \Lambda \in O(3,1)$$

with $\det(A \cdot B) = \det A \det B$ and $\det A^T = \det A$ we have

$$\Rightarrow \underline{(\det \Lambda)^2 = 1} \quad (\text{after canceling } \det \eta = -1 \text{ on both sides})$$

in $SO(3,1)$ labels the number of + and - signs in the metric, $\underline{s} = \det \eta = +1$

• the dimension of $SO(3,1)$ is the same as $O(4)$.

$$\dim O(4) = \frac{4(4-1)}{2} = 6 = 3 \text{ generators for rotations}$$

+ 3 " for boosts