

Why is a linear diff. (Schrödinger) eq. associated to KdV?

• formalism to construct a linear diff eq associated to a non-linear one: Lax-method

• before introducing this: an intuitive answer for KdV:

KdV - mKdV relation:

- in order to construct the infinite tower of conserved quantities for the KdV we used a second non-lin. diff. eq. the mKdV:

$$\underline{\partial_t u - u \partial_x u - \partial_x^3 u = 0} \quad \text{KdV}$$

$$+ \underline{u(x,t) = -6\lambda + i\sqrt{6}\partial_x \psi(x,t) + \psi^2(x,t)}$$

generalized Riccati trafo

$$\Rightarrow \underline{\partial_t \psi - (-6\lambda + \psi^2) \partial_x \psi - \partial_x^3 \psi = 0} \quad \text{mKdV}$$

(see p. 28 for $\lambda=0$)

• from the mKdV + Galilei-trafo (ε) & Taylor expansion in ε we constructed all H_n 's explicitly, so

solution mKdV \Rightarrow solution KdV

Q: When does " \Leftarrow " hold, i.e. when can one invert the Riccati trafo?

parametrise $V(u,t) = i\sqrt{6} \frac{\partial_x \psi(u,t)}{\psi(u,t)}$ for $\psi(u,t) \neq 0$ (**)

$$\Rightarrow \psi^2 - i\sqrt{6} \partial_x \psi = -6 \frac{(\partial_x \psi)^2}{\psi^2} - 6 \left(\frac{\partial_x^2 \psi}{\psi} - \frac{\partial_x \psi \partial_x \psi}{\psi^2} \right)$$

$$= -6 \frac{\partial_x^2 \psi}{\psi}$$

and thus

$$u(u,t) = -6\lambda - 6 \frac{\partial_x^2 \psi(u,t)}{\psi(u,t)}$$

$$\Leftrightarrow \boxed{\partial_x^2 \psi(u,t) + \left(\frac{1}{6} u(u,t) + \lambda \right) \psi(u,t) = 0}$$

Schrodinger eq. with pot. $V(u) = -\frac{1}{6} u(u,t)$

- if $\psi(u,t)$ solves this Schrodinger eq. for given $u(u,t)$ we can reconstruct $\psi(u,t)$ via (**):

$$\partial_x \psi(u,t) = -\frac{i}{\sqrt{6}} V(u,t) \psi(u,t)$$

$$\Leftrightarrow \psi(u,t) = \exp \left[-\frac{i}{\sqrt{6}} \int^x dy V(y,t) \right] \quad \text{ⓐ}$$

exercise: show that using this in the mKdV eq yields:

$$\psi^{-1} \left[\partial_t \psi + 4\lambda \partial_x \psi + \frac{1}{6} (\partial_x u) \psi - \frac{1}{3} u \partial_x \psi \right] = \text{const.}$$

- this is precisely eq. (*) on p. 3+ which we used to determine the t -dependence of ψ via the inverse scattering method (bel'and-Levitan eq.), using ⓐ we then have $\psi(u,t)$ too

so $\text{KdV} \xleftrightarrow[\text{eq.}]{\text{Schrodinger}}$ mKdV

The Lax-Pair Method

Goal: given a nonlinear PDE in x and t :

→ find a linear operator L with constant, that is t -indep. eigenvalues, that relates both to the PDE and the Schrödinger eq.

• this method is not constructive, it just formalises (and facilitates) to find the Lax-pair of operators L, B

• to draw an analogy let's remind ourselves to

* time evolution of operators in quantum mechanics:

given time τ and a Hamilton operator $H = H^\dagger$ that is not explicitly τ -dependent

⇒ time evolution is provided by the following

unitary operator $U(\tau) = e^{-iH\tau}$, $U^\dagger(\tau)U(\tau) = U U^\dagger = \mathbb{1}$

• Schrödinger picture

* states τ -dependent:

$$i\partial_\tau \psi(\tau) = H \psi(\tau)$$

$$\Rightarrow \underline{\psi(\tau) = U(\tau) \psi(0)}$$

* operators τ -indep:

$$\underline{A_S \psi(\tau) = \lambda \psi(\tau)} \quad \xleftrightarrow{U^\dagger}$$

• Heisenberg picture

* states τ -indep:

$$\psi = \psi(0)$$

* operators τ -dep:

$$A_H(\tau) = U^\dagger(\tau) A_S U(\tau)$$

$$\boxed{A_H(\tau) \psi(0) = \lambda \psi(0)}$$

If we are seeking an operator with time indep. eigenvalues

$$\partial_{\tau} \lambda = 0 \Rightarrow \partial_{\tau} A_{\#}(\tau) = 0, \quad U(\tau) = e^{+iH\tau}$$

$$\Leftrightarrow 0 = \partial_{\tau} (U^{\dagger}(\tau) A_{\#} U(\tau)) = \partial_{\tau} U^{\dagger}(\tau) A_{\#} U(\tau) + U^{\dagger} \partial_{\tau} A_{\#} U + U^{\dagger} A_{\#} \partial_{\tau} U \\ = U^{\dagger} (\partial_{\tau} A_{\#} + iH A_{\#} + A_{\#} (-iH)) U(\tau)$$

$$\Leftrightarrow \partial_{\tau} A_{\#} = i[A_{\#}, H] \quad (\partial_{\tau} A_{\#} = 0 \text{ by construction so } [A_{\#}, H] = 0)$$

def $B = -iH$ anti-Hermitian we have

$$\boxed{\partial_{\tau} A_{\#} = [B, A_{\#}]} \quad \text{I} \quad \text{"}\tau\text{-evolution of } A_{\#}\text{"}$$

$$\partial_{\tau} \psi = -iH \psi \Rightarrow \boxed{\partial_{\tau} \psi(\tau) = B \psi(\tau)} \quad \text{II} \quad \tau\text{-evolution of } \psi$$

$$\boxed{A_{\#} \psi(\tau) = \lambda \psi(\tau)} \quad \text{III} \quad \text{Schrodinger eq., eigenvalue eq.}$$

• the fact that A is τ indep is equiv to the fact that

\exists unitary trafo of $A_{\#}(\tau)$ that makes it τ -indep i.e. that

$$\text{basis: } A_{\#} \rightarrow U(\tau) A_{\#} U^{\dagger}(\tau) = U U^{\dagger} A_{\#} U U^{\dagger} = A_{\#} \tau\text{-indep}$$

* Lax pair: $\tau \rightarrow t$ (\neq Schrodinger time)

$$A_{\#} \rightarrow L(t)$$

$$-iH \rightarrow B(t)$$

satisfying the same set of eqs.

Lax-Operator

* we are looking for an operator $\mathcal{L}(t)$ that

- is Hermitian $\mathcal{L}(t)^\dagger = \mathcal{L}(t) \Rightarrow$ real eigenvalues λ

- has t -indep. eigenvalues

$$\boxed{\mathcal{L}(t) \psi(t) = -\lambda \psi(t) \quad | \text{I} \rangle, \lambda \neq \lambda(t)}$$

(otherwise we cannot determine the t -dependence of $\psi(t)$!)

$\Rightarrow \exists$ unitary operator $u(t)$: $\underline{u(t)^\dagger u(t) = u(t) u(t)^\dagger = \mathbb{1}}$

s.t. $\left\{ \begin{array}{l} \mathcal{L}(t) \rightarrow u(t)^\dagger \mathcal{L}(t) u(t) \\ \psi(t) \rightarrow u(t)^\dagger \psi(t) \end{array} \right\}$ become t -indep.

$$\Rightarrow 0 = \partial_t (u^\dagger \mathcal{L} u) = (\partial_t u^\dagger) \mathcal{L} u + u^\dagger \partial_t \mathcal{L} u + u^\dagger \mathcal{L} \partial_t u$$

$$\text{using } \underline{0 = \partial_t (u u^\dagger) = (\partial_t u) u^\dagger + u \partial_t u^\dagger}$$

$$\text{and defining } \mathcal{B}(t) \equiv -u(t) \partial_t u^\dagger(t) = +(\partial_t u) u^\dagger$$

$$\text{we have } 0 = u^\dagger (-u \partial_t u^\dagger \mathcal{L} + \partial_t \mathcal{L} + \mathcal{L} (\partial_t u) u^\dagger) u$$

$$\Leftrightarrow \boxed{\partial_t \mathcal{L}(t) = [\mathcal{B}(t), \mathcal{L}(t)]} \quad | \text{I} \rangle$$

$$\text{and } 0 = \partial_t u + u (\partial_t u^\dagger) u$$

$$\Leftrightarrow \underline{\partial_t u(t) = + \mathcal{B}(t) u(t)}$$

$$\text{or } \partial_t (u u^\dagger \psi(t)) = 0 \Leftrightarrow \partial_t \psi(t) = -u(t) (\partial_t u^\dagger(t)) \psi(t)$$

$$\Leftrightarrow \boxed{\partial_t \psi(t) = \mathcal{B}(t) \psi(t)} \quad | \text{II} \rangle$$

• the operators $L(t)$ and $B(t)$ are called Lax pair and the eq. I-III Lax eq.. Usually L and B are differential operators

* the art is to choose L, B s.th. I is the non-linear PDE in $u(x,t)$ we want to solve (e.g. KdV) s.th. $L(t)$ is linear in $u(x,t)$

so that III defines a (linear) Schrödinger eq with potential $u(x,t)$ (B is not necessarily linear in $u(x,t)$).

Then eq. II gives the t -dependence of the Schrödinger wave function $\psi(x,t)$ (as we did for KdV)

→ using inverse scattering & Gel'fand Levitan we can then find $u(x,t)$ from $u(x,t=0)$!

Examples for Lax pairs :

Choose $\boxed{L(t) = \partial_x^2 + \frac{1}{6} u(x,t)}$

m p. 56 is the Schrödinger eq we have solved for u being a solution of $u_{tt} = u u_x$

Example 1)

with $\boxed{B(t) = \partial_x + \text{const}}$

$$\Rightarrow \partial_t L = [B, L] = [\partial_x + \text{const}, \partial_x^2 + \frac{1}{6} u(x,t)]$$

$$\Leftrightarrow \frac{1}{6} (\partial_t u) = \frac{1}{6} (\partial_x u) \quad \text{I} \quad \text{chiral wave eq.}$$

(s. p. 34), linear PDE

with time evolution

$$\underline{\partial_t \psi(x,t) = \partial_x \psi(x,t)} \quad \text{II}$$

Example 2) choose the same $L(t)$ above

and ansatz $\boxed{B(t) = 4 \partial_x^3 + \frac{1}{2} ((\partial_x u) + 2u \partial_x) + \text{const}}$

↑ ↑
these coeff. are chosen such that I will give back

* Note the similarity between the $B_{m=0,1}$ and the differential operators in the 2 Poisson brackets (e.g. p. 25)

* scaling behaviour : p. 31 $\dim[u] = -2 = \dim[\partial_x^2]$

$\Rightarrow L(t)$ above has a definite scaling behaviour

$\Rightarrow B(t)$ has scaling behaviour $\dim[\partial_x^3] = -3 = \dim[\partial_x u]$

it is the same as $[\partial_t] = -3$

In order to check that B_1 gives kdv from eq. I

we need to compute the following commutators (exercise):

$$[\partial_x, u] = \partial_x u - u \partial_x = (\partial_x u) + u \partial_x - u \partial_x = (\partial_x u)$$

$$[\partial_x^2, u] = (\partial_x^2 u) + 2(\partial_x u) \partial_x$$

$$[\partial_x^3, u] = (\partial_x^3 u) + 3(\partial_x^2 u) \partial_x + 3(\partial_x u) \partial_x^2$$

$$[\partial_x^2, (\partial_x u)] = (\partial_x^3 u) + 2(\partial_x^2 u) \partial_x$$

$$[\partial_x^2, u \partial_x] = (\partial_x^2 u) \partial_x + 2(\partial_x u) \partial_x^2$$

$$[(\partial_x u), u] = 0$$

and a constant

$$[u \partial_x, u] = u(\partial_x u)$$

commutes with everything

We also have $[\partial_x^k, \partial_x^l] = 0$ of course

We can now compute $\partial_t \mathcal{L} = [B_1, \mathcal{L}] \Leftrightarrow$ kdv:

$$\bullet 6 \partial_t \mathcal{L} \llbracket 1 \rrbracket = 6 \partial_t (\partial_x^2 + \frac{1}{6} u u_x) \llbracket 1 \rrbracket = \boxed{(\partial_t u u_x)} \llbracket 1 \rrbracket$$

$$\bullet 6 [B_1, \mathcal{L}] \llbracket 1 \rrbracket = 6 [4 \partial_x^3 + \frac{1}{2} (\partial_x u) + u \partial_x + \cancel{u \partial_x}, \partial_x^2 + \frac{1}{6} u] \llbracket 1 \rrbracket$$

$$= 4 \{ (\partial_x^3 u) + 3(\partial_x^2 u) \partial_x + 3(\partial_x u) \partial_x^2 \} \llbracket 1 \rrbracket$$

$$+ 3 \{ -(\partial_x^3 u) - 2(\partial_x^2 u) \partial_x \} \llbracket 1 \rrbracket - 6 \{ (\partial_x^2 u) \partial_x + 2(\partial_x u) \partial_x^2 \} \llbracket 1 \rrbracket$$

$$+ u(\partial_x u) \llbracket 1 \rrbracket = \boxed{\partial_x^3 u + u \partial_x u} \llbracket 1 \rrbracket \quad I \Leftrightarrow \text{kdv} \checkmark$$

$$\text{II: } \partial_t \psi = B_n \psi(t)$$

$$= 4 \partial_x^3 \psi + \frac{1}{2} (\partial_x u) \psi + u \partial_x \psi + \text{const} \psi$$

using $\partial_x \overline{u}$ (Schrödinger): $\partial_x^3 \psi + \frac{1}{6} (\partial_x u) \psi + \frac{1}{6} u \partial_x \psi = -12 \psi$

we obtain

$$\partial_t \psi = -41 \partial_x^3 \psi - \frac{1}{6} (\partial_x u) \psi + \frac{1}{3} u \partial_x \psi + \text{const} \psi$$

for the time evolution of $\psi(x,t)$, which equals eq. (4) on p 37.

Lax - Pairs of the KdV Hierarchy

recall (pages 33+34) the chain of eqs:

$$\partial_t u = \{u(x), H_n\}_1 = \{u(x), H_{n+1}\}_2$$

$$\Leftrightarrow \boxed{\partial_t u = \partial_x \frac{\delta H_{n+1}}{\delta u(x)}}$$

$n=0$ $\partial_t u = \partial_x u$ d'Alambert wave eq.

$n=1$ $\partial_t u = \partial_x^3 u + u \partial_x u$ KdV

$n=2$ $\partial_t u = \partial_x^5 u + \frac{4}{3} u \partial_x^3 u + \frac{10}{3} (\partial_x u) (\partial_x u^2) + \frac{5}{6} u^2 \partial_x u$

etc.

- One can show that for each of these non-lin PDE of the KdV hierarchy one can construct an operator

$$B_n(t) \text{ s.t. } \boxed{\partial_t \mathcal{L} = [B_n, \mathcal{L}]}$$
 gives the n -th eq.

Remarks: * all these non-linear PDE can be solved with the same Schrödinger eq.

$$\text{I} \quad \underline{\underline{\mathcal{L}(t) = -\lambda \psi(t)}}$$

$$\text{with our } \underline{\underline{\mathcal{L}(t) = \partial_x^2 + \frac{1}{6} u(x,t)}}$$

using the inverse scattering method.

* However, for each u the t -evolution of $\psi(x,t)$ changes and is given by

$$\text{II} \quad \partial_t \psi(x,t) = B_u(t) \psi(x,t)$$

Exercise: determine $B_{u=2}$

$$\begin{aligned} \text{Note that because } \partial_t \mathcal{L} &= \frac{1}{6} \partial_t u = \partial_x \frac{\delta H_{n+1}}{\delta u(x)} \\ &= [B_u, \mathcal{L}] \end{aligned}$$

and the fact that H_{n+1} has a defined scaling behaviour (p. 31: $\text{dim}[H_n] = -2(n+1) - 1$) also B_u has a defined scaling behaviour (which?).

This allows to determine the coefficient functions $b_j(u)$ in the Ansatz $B_u(t) \sim \partial_x^{2n+1} + \sum_{j=1}^n (b_j(u) \partial_x^{2j-1} + \partial_x^{2j-1} b_j(u))$